

Deformations with constant Milnor number and multiplicity of non-degenerate complex hypersurfaces

Marcelo José Saia *

Departamento de Matemática, Instituto de Ciências Matemáticas e de Computação, Universidade de São Paulo - Campus de São Carlos, Caixa Postal 668, 13560-970, São Carlos SP, Brazil
E-mail: mjsaia@icmc.sc.usp.br

J. N. Tomazella

Departamento de Matemática, Universidade Federal de São Carlos, Rodovia Washington Luis, km 235, Caixa Postal 676, São Carlos, SP, Brazil
E-mail: tomazela@dm.ufscar.br

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We investigate the constancy of the Milnor number of one parameter deformations of holomorphic germs of functions $f : (\mathbb{C}^n, 0) \rightarrow (\mathbb{C}, 0)$ with isolated singularity, in terms of some Newton polyhedra associate to such germs.

We show that if the Jacobian ideals $J(f_t) = \langle \partial f_t / \partial x_1, \dots, \partial f_t / \partial x_n \rangle$ of a deformation $f_t(x) = f(x) + \sum_{s=1}^{\ell} \delta_s(t) g_s(x)$ are non-degenerate on some fixed Newton polyhedron Γ_+ , then this family is μ -constant for small values of t , if and only if all germs g_s have non-decreasing Γ -order with respect to f .

For the μ -constant families of germs obtained as a consequence of these results we have a positive answer for the Zariski's question: *Whether for a hypersurface singularity the multiplicity is an invariant of the topological type?*

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1. μ -CONSTANT DEFORMATIONS AND MULTIPLICITY

The determination of conditions for a family of isolated singularity germs $f_t : (\mathbb{C}^n, 0) \rightarrow (\mathbb{C}, 0)$ to have constant Milnor number is one of the most interesting questions in singularity theory. This question is being investigated by several authors, Varchenko gives in [13] a full answer for this question for the case of weighted homogeneous germs with isolated singularity.

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THEOREM 1.1. [13] *Let $F(x, t) = f(x) + \sum_{s=1}^{\ell} \delta_s(t)g_s(x)$ be a deformation of a weighted homogeneous polynomial germ $f : (\mathbb{C}^n, 0) \rightarrow (\mathbb{C}, 0)$ with isolated singularity at 0, where $\delta_s : (\mathbb{C}, 0) \rightarrow (\mathbb{C}, 0)$ and $g_s : (\mathbb{C}^n, 0) \rightarrow (\mathbb{C}, 0)$ are holomorphic germs of functions and $\delta_s \neq 0$. Then the family $f_t(x) = F(x, t)$ is μ -constant for small values of t , if and only if all monomials of each germ g_s have weighted degree higher or equal than the weighted degree of f .*

Another number that is associated to germs of functions is the multiplicity, and Zariski asked in [15] the following question: *Whether for a hypersurface singularity the multiplicity is an invariant of the topological type?*

A positive answer for Zariski's question was previously known for the case of plane curves and for homogeneous surfaces. In the case of families of semi quasi homogeneous germs, a positive answer for Zariski's question is showed by Greuel in [4] and independently by D. O'Shea in [8]. Both authors applied the theorem 1.1 of Varchenko, but used different methods.

THEOREM 1.2. [4], [8] *Let $f_t(x) = f(x) + \sum_{s=1}^{\ell} \delta_s(t)g_s(x)$ be a μ -constant deformation of a weighted homogeneous polynomial germ $f : (\mathbb{C}^n, 0) \rightarrow (\mathbb{C}, 0)$ with isolated singularity at 0. Then the family $F(x, t) = f_t(x)$ is m -constant (m denotes the multiplicity).*

In this article we investigate the relationship between these questions and some Newton polyhedra associate to the germ f .

The use of the Newton polyhedron of a germ f to give sufficient conditions for the μ -constancy was done by Kouchnirenko in [5]. Yoshinaga in [14] and Damon-Gaffney in [3] also dealt with this Newton polyhedron to show sufficient conditions for the topological triviality.

Here we first show necessary and sufficient conditions for the μ -constancy in terms of the Newton polyhedron defined by the Jacobian ideal of f . Then we show necessary and sufficient conditions for the μ -constancy of families of germs which are non-degenerate on some fixed Newton polyhedron Γ_+ (see 4.4), we show that the family is μ -constant for small values of t , if and only if all germs g_s have non-decreasing Γ -order with respect to f .

In the final section we apply these results to show that these μ -constant families also have constant multiplicity, giving a positive answer for Zariski's question for this kind of germs.

2. μ -CONSTANT DEFORMATIONS AND INTEGRAL CLOSURE

We fix a system of local coordinates x of \mathbb{C}^n , consider the ring \mathcal{O}_n of holomorphic germs $f : (\mathbb{C}^n, 0) \rightarrow \mathbb{C}$ and denote by m_n its maximal ideal. Due to the identification between \mathcal{O}_n and the ring of convergent power series $\mathbb{C}\{x_1, \dots, x_n\}$ we identify a germ $f \in \mathcal{O}_n$ with its power series $f(x) = \sum a_\alpha x^\alpha$, with $x^\alpha = x_1^{\alpha_1} \dots x_n^{\alpha_n}$.

The Milnor number of a germ f , denoted by $\mu(f)$, is algebraically defined as the $\dim_{\mathbb{C}} \mathcal{O}_n/J(f)$, where $J(f)$ denotes the ideal generated by the partial derivatives $\{\partial f/\partial x_1,$

$\dots, \partial f / \partial x_n \}$. A deformation $F: (\mathbb{C}^n \times \mathbb{C}, 0) \rightarrow (\mathbb{C}, 0)$ of f is μ -constant if $\mu(f_t) = \mu(f)$ for small values of t . We denote by $J(F) = \langle \partial F / \partial x_1, \dots, \partial F / \partial x_n \rangle$, the ideal generated by the partial derivatives of F with respect to the variables x_1, \dots, x_n .

Greuel gives in [4] a full characterization of μ -constant deformations of f in terms of the integral closure of the Jacobian ideal of $J(F)$.

The **integral closure** of an ideal I in a ring R , is the ideal \bar{I} , of the elements $h \in R$ which satisfies a relation $h^k + a_1 h^{k-1} + \dots + a_{k-1} h + a_k = 0$, with $a_i \in I^i$.

Teissier gave in [10, p.288] the following characterization for the integral closure of ideals in $R = \mathcal{O}_n$.

PROPOSITION 2.1. *If I is an ideal in \mathcal{O}_n , the following statements are equivalent:*

1. $h \in \bar{I}$;
2. for each system of generators h_1, \dots, h_r of I there exists a neighbourhood U of 0 and a constant $C > 0$ such that $|h(x)| \leq C \sup\{|h_1(x)|, \dots, |h_r(x)|\}$, for all $x \in U$;
3. for each analytic curve $\varphi: (\mathbb{C}, 0) \rightarrow (\mathbb{C}^n, 0)$, $h \circ \varphi$ lies in $(\varphi^*(I)) \mathcal{O}_1$.

The item 3 of this proposition is called *valuative criterion* since it is equivalent to the condition $\nu(h \circ \varphi) \geq \inf\{\nu(h_1 \circ \varphi), \dots, \nu(h_r \circ \varphi)\}$, where ν denotes the usual valuation of a complex curve. In this case, the valuation is the multiplicity of the curve, see section 5 for the definition of multiplicity.

THEOREM 2.1. [4, p.161] *Let $F: (\mathbb{C}^n \times \mathbb{C}, 0) \rightarrow (\mathbb{C}, 0)$ be a one parameter deformation of a holomorphic germ $f: (\mathbb{C}^n, 0) \rightarrow (\mathbb{C}, 0)$ with isolated singularity. The following statements are equivalent*

1. F is a μ -constant deformation of f ;
2. $\frac{\partial F}{\partial t} \in \overline{J(F)}$;
3. $\frac{\partial F}{\partial t} \in \sqrt{J(F)}$, here $\sqrt{J(F)}$ denotes the radical of $J(F)$;
4. the polar curve of F with respect to $\{t = 0\}$ does not split, i.e.,

$$\left\{ (x, t) \in \mathbb{C}^n \times \mathbb{C} \mid \frac{\partial F}{\partial x_i}(x, t) = 0, \forall i = 1, \dots, n \right\} = \{0\} \times \mathbb{C} \text{ near } (0, 0).$$

3. μ -CONSTANT DEFORMATIONS AND NEWTON POLYHEDRA

We show here necessary and sufficient conditions for a deformation $F(x, t)$ to be μ -constant. These conditions will be given in terms of some suitable Newton polyhedra associate to the germ f .

For a germ $f(x) = \sum a_k x^k$, we define $\text{supp } f = \{k \in \mathbb{Z}^n : a_k \neq 0\}$. For an ideal I in \mathcal{O}_n , we call $\text{supp } I = \cup \{\text{supp } g : g \in I\}$.

DEFINITION 3.1. The Newton polyhedron of I , denoted by $\Gamma_+(I)$, is the convex hull in \mathbb{R}_+^n of the set

$$\cup \{k + v : k \in \text{supp } I, v \in \mathbb{R}_+^n\}.$$

$\Gamma(I)$ denotes the union of all compact faces of $\Gamma_+(I)$.

A germ g is of **non-decreasing Newton order** with respect to $\Gamma_+(I)$ if $\Gamma_+(g) \subseteq \Gamma_+(I)$.

From the integral closure of the Jacobian ideal $J(f)$ we define the polyhedron $T(f)$, which is a key tool to study the μ -constancy.

DEFINITION 3.2. $T(f)$ is the convex hull in \mathbb{R}_+^n of $\cup \{m + v : x^m \in \overline{J(f)} \text{ and } v \in \mathbb{R}_+^n\}$.

In the next lemma we show a necessary condition for the μ -constancy of families defined by first order deformations.

LEMMA 3.1. *Let $F(x, t) = f(x) + tg(x)$ be a first order deformation of a complex germ f with isolated singularity. A necessary condition for the μ -constancy of the family f_t is $\Gamma_+(g) \subseteq T(f)$.*

Proof: If $\Gamma_+(g) \not\subseteq T(f)$, it follows from the valuative criterion that there exists an holomorphic curve $\gamma: (\mathbb{C}, 0) \rightarrow (\mathbb{C}^n, 0)$, such that

$$\nu(g \circ \gamma) < \inf \left\{ \nu \left(\frac{\partial f}{\partial x_i} \circ \gamma \right), \forall i = 1, \dots, n \right\}.$$

We define the curve $\psi: (\mathbb{C}, 0) \rightarrow (\mathbb{C}^n \times \mathbb{C}, 0)$ as $\psi = (\gamma, 0)$. Since $\frac{\partial F}{\partial x_i} = \frac{\partial f}{\partial x_i} + t \frac{\partial g}{\partial x_i}$, we obtain $\frac{\partial F}{\partial x_i} \circ \psi = \frac{\partial f}{\partial x_i} \circ \gamma$ and the result follows from item 3 of the Proposition 2.1 and the Theorem 2.1. ■

We describe now sufficient conditions for the μ constancy.

Yoshinaga in [14] gave conditions for the topological triviality of families of type $F(x, t) = f(x) + tg(x)$ in terms of the gradient polyhedron $\Lambda_+(f)$, defined as the convex hull of the set

$$\cup \left\{ m + v, : v \in +\mathbb{R}_+^n \text{ and } \left| x_1 \frac{\partial f}{\partial x_1} \right| + \dots + \left| x_n \frac{\partial f}{\partial x_n} \right| \geq \mathcal{E} |x^m| \right\},$$

for a positive $\mathcal{E}(m)$ in a neighbourhood of the origin in \mathbb{C}^n . In the theorem 1.6 of [14] it is shown that if $\Gamma_+(g) \subset \Lambda_+(f)$, then $F(x, t) = f(x) + tg(x)$ is topologically trivial for sufficiently small values of t . Damon-Gaffney in [3] also gave similar results for the topological triviality.

We remark that if a germ g satisfies the condition $\Gamma_+(g) \subset \Lambda_+(f)$, it is equivalent to say that g is in integral closure of the ideal generated by the system $\left\{x_1 \frac{\partial f}{\partial x_1}, \dots, x_n \frac{\partial f}{\partial x_n}\right\}$. Since this ideal is in the integral closure of the ideal $J(F)$, we conclude from the results of Yoshinaga, Damon-Gaffney and the Theorem 2.1, the following

PROPOSITION 3.1. *Let $F(x, t) = f(x) + \sum_{s=1}^{\ell} \delta_s(t)g_s(x)$, be a deformation of f with isolated singularity at 0. If $\Gamma_+(g_s) \subset \Lambda_+(f)$ for all $s = 1, \dots, \ell$, then $F(x, t)$ is μ -constant for sufficiently small values of t .*

Next we show a sufficient condition for the μ -constancy in terms of the polyhedron $T(f)$.

PROPOSITION 3.2. *Let $F(x, t) = f(x) + \sum_{s=1}^{\ell} \delta_s(t)g_s(x)$ be a deformation of a complex germ f with isolated singularity. If $g_s(x) \in m_n$ and $\Gamma_+(J(g_s)) \subseteq T(f)$ for all $s = 1, \dots, \ell$, then $F(x, t)$ is μ -constant for small values of t .*

Proof: Suppose that $\Gamma_+(J(g_s)) \subseteq T(f)$, from the item 2 of the Proposition 2.1, we obtain that for each $i = 1, \dots, n$ and $s = 1, \dots, \ell$ there exist a neighbourhood $U_{i,s}$ of 0 and a constant $C_{i,s} > 0$, such that $\left|\frac{\partial g_s}{\partial x_i}\right| \leq C_{i,s} \sup \left\{\left|\frac{\partial f}{\partial x_1}\right|, \dots, \left|\frac{\partial f}{\partial x_n}\right|\right\}$, then

$$\sum_{s=1}^{\ell} |\delta_s(t)| \left|\frac{\partial g_s}{\partial x_i}\right| \leq \sum_{s=1}^{\ell} |\delta_s(t)| C_{i,s} \sup \left\{\left|\frac{\partial f}{\partial x_1}\right|, \dots, \left|\frac{\partial f}{\partial x_n}\right|\right\}.$$

Therefore, for all x in a neighbourhood $U \subset U_{i,s}$ for all $s = 1, \dots, \ell$ and $i = 1, \dots, n$,

$$\begin{aligned} \sup_i \left|\frac{\partial F}{\partial x_i}\right| &= \sup_i \left|\frac{\partial f}{\partial x_i} + \sum_{s=1}^{\ell} \delta_s(t) \cdot \frac{\partial g_s}{\partial x_i}\right| \geq \sup_i \left|\frac{\partial f}{\partial x_i}\right| - \sup_i \sum_{s=1}^{\ell} |\delta_s(t)| \left|\frac{\partial g_s}{\partial x_i}\right| \\ &\geq \sup_i \left|\frac{\partial f}{\partial x_i}\right| - \sum_{s=1}^{\ell} |\delta_s(t)| C_{i,s} \sup_i \left\{\left|\frac{\partial f}{\partial x_i}\right|\right\} \\ &\geq (1 - \sum_{s=1}^{\ell} |\delta_s(t)| C_{i,s}) \sup_i \left|\frac{\partial f}{\partial x_i}\right| \\ &\geq (1 - \alpha) \sup_i \left|\frac{\partial f}{\partial x_i}\right|, \end{aligned}$$

for some $0 < \alpha < 1$ with $\sum_{s=1}^{\ell} |\delta_s(t)| C_{i,s} \leq \alpha$ for all $i = 1, \dots, n$ and $s = 1, \dots, \ell$.

This inequality implies that $\left\langle \frac{\partial f}{\partial x_1}, \dots, \frac{\partial f}{\partial x_n} \right\rangle \subset \left\langle \frac{\partial F}{\partial x_1}, \dots, \frac{\partial F}{\partial x_n} \right\rangle$.

Now we show that for each analytic curve $\psi : (\mathbb{C}, 0) \rightarrow (\mathbb{C}^{n+1}, 0)$,

$$\nu \left(\frac{\partial F}{\partial t} \circ \psi \right) \geq \min_i \left\{ \nu \left(\frac{\partial F}{\partial x_i} \circ \psi \right) \right\}.$$

We write $\psi = (\varphi, \lambda)$, with $\varphi : (\mathbb{C}, 0) \rightarrow (\mathbb{C}^n, 0)$ and $\lambda : (\mathbb{C}, 0) \rightarrow (\mathbb{C}, 0)$, hence

$$\nu \left(\frac{\partial F}{\partial t} \circ \psi \right) \geq \min_s \{ \nu(\delta'_s \circ \lambda) + \nu(g_s \circ \varphi) \} \geq \min_s \{ \nu(g_s \circ \varphi) \}.$$

From the hypothesis that $g_s(x) \in m_n$ and $\Gamma_+(J(g_s)) \subseteq T(f)$, we obtain that $\Gamma_+(g_s) \in T(f)$, hence $g_s \in \left\langle \frac{\partial f}{\partial x_1}, \dots, \frac{\partial f}{\partial x_n} \right\rangle$.

Therefore $\nu(g_s \circ \varphi) \geq \min_i \left\{ \nu \left(\frac{\partial f}{\partial x_i} \circ \varphi \right) \right\} \geq \min_i \left\{ \nu \left(\frac{\partial F}{\partial x_i} \circ \psi \right) \right\}$, and

$$\nu \left(\frac{\partial F}{\partial t} \circ \psi \right) \geq \min_s \{ \nu(g_s \circ \varphi) \} \geq \min_i \left\{ \nu \left(\frac{\partial F}{\partial x_i} \circ \psi \right) \right\}$$

and the result follows from the Proposition 2.1. \blacksquare

We see in the example below that the conditions shown in the Propositions 3.1 and 3.2 gives rise to different classes of μ -constant deformations $F(x, t) = f(x) + tg(x)$.

EXAMPLE 3.1. Let $f(x, y) = y^7 + x^4y + x^9$.

From the theorem 1.3 of Yoshinaga (see the Corollary 4.1), we know that $\Lambda_+(f) = \Gamma_+(f)$ is the polygon with vertices $(0, 7)$, $(4, 1)$ and $(9, 0)$. From the Corollary 4.1 we see that the polygon $T(f)$ has vertices $(0, 6)$, $(3, 1)$ and $(4, 0)$.

If we consider $g(x, y) = x^2y^4$, $\Gamma_+(g) \subset \Lambda_+(f)$, hence the deformation $F(x, y, t) = y^7 + x^4y + x^9 + tx^2y^4$ is μ -constant from the Proposition 3.1, but $\Gamma_+(J(g)) \not\subset T(f)$.

We also see in this example that the condition $\Gamma_+(J(g)) \subset T(f)$ does not imply that $\Gamma_+(g) \subset \Lambda_+(f)$, for this, consider $g(x, y) = x^6$. Here we conclude that the deformation $F(x, y, t) = y^7 + x^4y + x^9 + tx^6$ is μ -constant from the Proposition 3.2, and $\Gamma_+(g) \not\subset \Lambda_+(f)$.

4. THE NON-DEGENERATE CASE

In this section we describe how to obtain μ -constant deformations in terms of non-degeneracy conditions given by some Newton polyhedra associate to the germ f .

Let I be an ideal of finite codimension in \mathcal{O}_n , i.e, $\dim_{\mathbb{C}} \mathcal{O}_n/I < \infty$. For each face $\Delta \subseteq \Gamma(I)$ we denote by $C(\Delta)$ the cone given by the union of half-rays emanating from the origin and passing through Δ . We call \mathcal{A}_Δ the subring with unity of \mathcal{O}_n given by $\mathcal{A}_\Delta = \{g \in \mathcal{O}_n : \text{supp } g \subseteq C(\Delta) \cap \mathbb{Z}^k\}$.

If D is a fixed subset of $\Gamma_+(I)$ and $g = \sum_k a_k x^k$, we set $g_D = \sum_{k \in D} a_k x^k$.

DEFINITION 4.1. A subset $\Delta \subset \Gamma_+(I)$ is Newton non-degenerate if the ideal generated by $g_{1_\Delta}, g_{2_\Delta}, \dots, g_{s_\Delta}$ has finite codimension in \mathcal{A}_Δ .

DEFINITION 4.2. An ideal I is *Newton non-degenerate* if there exists a system of generators $\{g_1, \dots, g_s\}$ of I such that, for each compact face $\Delta \subseteq \Gamma(I)$, the ideal I_Δ generated by $\{g_{1_\Delta}, \dots, g_{s_\Delta}\}$ has finite codimension in \mathcal{A}_Δ .

We denote by $C(\bar{I})$ the convex hull in \mathbb{R}_+^n of the set $\cup \{m : x^m \in \bar{I}\}$.

We remark that if I is the ideal generated by $\left\{ x_1 \frac{\partial f}{\partial x_1}, \dots, x_n \frac{\partial f}{\partial x_n} \right\}$, then $C(\bar{I}) = \Lambda_+(f)$ and $T(f) = C(\overline{J(f)})$, where $J(f)$ is the Jacobian ideal of f .

A germ $g = \sum_k a_k x^k$ is *Newton non-degenerate*, if the ideal generated by the system $\{x_1 \partial g / \partial x_1, \dots, x_n \partial g / \partial x_n\}$ is of finite codimension in \mathcal{O}_n and is Newton non-degenerate.

When the germ f is Newton non-degenerate we have the following

COROLLARY 4.1. *Suppose that $f : (\mathbb{C}^n, 0) \rightarrow (\mathbb{C}, 0)$ is a Newton non-degenerate germ with an isolated singularity. If each g_s has non-decreasing Newton order with respect to $\Gamma_+(f)$, the deformation $f(x) + \sum_{s=1}^{\ell} \delta_s(t) g_s(x)$ is μ -constant for sufficiently small values of t .*

When the Jacobian ideal $J(f)$ is Newton non-degenerate we also have the following:

COROLLARY 4.2. *Suppose that the system $\{\partial f / \partial x_1, \dots, \partial f / \partial x_n\}$ of generators of the Jacobian ideal $J(f)$ is Newton non-degenerate and $\Gamma_+(J(g_s)) \subseteq \Gamma_+(J(f))$ for all s . Then $F(x, t)$ is μ -constant for small values of t .*

The proof of these results is a direct consequence of the Propositions 3.1 (or 3.2) and the following

THEOREM 4.1. [9] *Let I be an ideal with finite codimension in \mathcal{O}_n . Then $C(\bar{I}) \subseteq \Gamma_+(I)$. The equality holds if and only if I is Newton non-degenerate.*

The next example shows that these two conditions are not enough to give all μ -constant deformations of any germ with isolated singularity.

EXAMPLE 4.1. Briançon and Speder showed in [1] that the family of hypersurfaces $X_t \in \mathbb{C}^3$ defined by the equations $f_t(x, y, z) = z^5 + y^7 x + x^{15} + t y^6 z = 0$ has constant topological type, but the monomial $y^6 z$ does not satisfies the condition of the Corollary 4.2. We can not apply the Corollary 4.1 either, since f is not Newton non-degenerate because the ideal generated by the system $\{x \partial f / \partial x, y \partial f / \partial y, z \partial f / \partial z\}$ does not have finite codimension in \mathcal{O}_n .

The germ $f(x, y, z) = z^5 + y^7 x + x^{15}$ has isolated singularity at 0 and is weighted homogeneous of weights $(1, 2, 3)$ and degree $d(f) = 15$, hence the μ -constancy of this family follows from the Theorem 1.1 of Varchenko.

In order to generalize these results for a bigger class of germs that contains the Newton non-degenerate germs and also the class of semi weighted homogeneous germs, we apply the results of Bivia-Fukui-Saia, given in [2] to show a necessary and sufficient condition for the μ -constancy of families defined by germs which are non-degenerate on some Newton polyhedron. We recover here the basic results for this definition.

A subset $\Gamma_+ \subseteq \mathbb{R}_+^n$ is a *Newton polyhedron* if there exist some $k_1, \dots, k_r \in \mathbb{Q}_+^n$ such that Γ_+ is the convex hull in \mathbb{R}_+^n of the set $\{k_i + v : v \in \mathbb{R}_+^n, i = 1, \dots, r\}$ and Γ_+ intersects all the coordinate axis. We call Γ the union of the compact faces of Γ_+ , Γ_- the set $\mathbb{R}^n - \Gamma_+$ and $V_n(\Gamma_-)$ denotes the n -dimensional volume of Γ_- . From the boundary of a Newton

polyhedron $\Gamma_+ \subseteq \mathbb{R}^n$ we construct a piecewise-linear function $\phi_\Gamma : \mathbb{R}^n \rightarrow \mathbb{R}$ with the following properties:

1. ϕ_Γ is linear on each cone $C(\Delta)$, where Δ is a compact face of Γ ;
2. ϕ_Γ takes positive integer values on the lattice points of $\mathbb{R}_+^n - \{0\}$;
3. there exists a positive integer M such that $\phi_\Gamma(k) = M$, for all $k \in \Gamma$.

This map ϕ_Γ induces a *Newton filtration* of $\mathcal{O}_n = \mathcal{A}_0 \supseteq \mathcal{A}_1 \supseteq \mathcal{A}_2 \supseteq \dots$, by the ideals $\mathcal{A}_q = \{g \in \mathcal{O}_n : \text{supp } g \subseteq \phi_\Gamma^{-1}(q + \mathbb{N})\}$, for all $q \in \mathbb{N}$, see [5](2.1). For any compact face Δ of Γ , this filtration induces a filtration on \mathcal{A}_Δ in a natural way.

DEFINITION 4.3. The Γ -order of a germ $g = \sum_k a_k x^k$, with respect to the filtration induced by Γ is defined as

$$d(g) = \min\{\phi_\Gamma(k) : k \in \text{supp } g\} = \max\{q : g \in \mathcal{A}_q\}.$$

The *principal part of g* is the polynomial $\text{in}(g) = \sum a_k x^k$ such that $\phi_\Gamma(k) = d(g)$. Given a face Δ of Γ , the *principal part of g over Δ* , denoted by $\text{in}_\Delta(g)$, is the polynomial

$$\text{in}_\Delta(g) = \sum \{a_k x^k : k \in \text{supp } g \cap C(\Delta) \text{ and } \phi_\Gamma(k) = d(g)\}.$$

DEFINITION 4.4. A system of generators g_1, \dots, g_s of an ideal I is *non-degenerate on Γ_+* if, for each compact face $\Delta \subseteq \Gamma$, the ideal of \mathcal{A}_Δ generated by $\text{in}_\Delta(g_1), \dots, \text{in}_\Delta(g_s)$ has finite codimension in \mathcal{A}_Δ . When the system g_1, \dots, g_s does not satisfy the above definition, we say that this system is *degenerate on Γ_+* .

We remark that this definition depends of the system of generators, while the definition of Newton non-degeneracy does not depend of the system on generators of the ideal.

The next theorem is essential to prove the main results of this section.

THEOREM 4.2. ([2], Theorem 3.3.) *Let g_1, \dots, g_n be a system of generators of an ideal I with finite codimension in \mathcal{O}_n and let $\Gamma_+ \subseteq \mathbb{R}^n$ be a Newton polyhedron. If M is the value on Γ of the filtration induced by Γ_+ and $d_1 = d(g_1), \dots, d_n = d(g_n)$ are the levels of the given set of generators of I with respect to this filtration, then*

1. $\dim_{\mathbb{C}} \mathcal{O}_n/I \geq \frac{d_1 \dots d_n}{M^n} n! V_n(\Gamma_-)$;
2. the equality holds if, and only if the system g_1, \dots, g_n is non-degenerate on Γ_+ .

In the sequel we consider a deformation $f_t(x) = f(x) + \sum_{s=1}^{\ell} \delta_s(t) g_s(x)$, of a germ $f : (\mathbb{C}^n, 0) \rightarrow (\mathbb{C}, 0)$ with isolated singularity at 0 and fix a Newton polyhedron Γ_+ .

We denote by D_i, D_i^s, D_{ti} , the Γ -order of the partial derivatives $\frac{\partial f}{\partial x_i}, \frac{\partial g_s}{\partial x_i}, \frac{\partial f_t}{\partial x_i}$ respectively.

THEOREM 4.3. *Suppose that the system of generators $\{\partial f/\partial x_1, \dots, \partial f/\partial x_n\}$ of the Jacobian ideal $J(f)$ is non-degenerate on Γ_+ . If $D_i^s \geq D_i$ for all $i = 1, \dots, n$ and all $s = 1, \dots, \ell$, then, for small values of t , the system of generators $\{\partial f_t/\partial x_1, \dots, \partial f_t/\partial x_n\}$ of each Jacobian ideal $J(f_t)$ is non-degenerate on Γ_+ . Moreover, $\mu(f_t)$ is constant.*

Proof: Suppose first that $D_i^s > D_i$ for all $i = 1, \dots, n$ and all $s = 1, \dots, \ell$, hence, $D_{ti} = D_i$ for all $i = 1, \dots, n$ and, for all t the principal part of each $\partial f_t/\partial x_i$ is equal to the principal part of $\partial f/\partial x_i$. From the non-degeneracy of $J(f)$ on Γ_+ , we obtain the non-degeneracy of each Jacobian ideal $J(f_t)$ and the equality $\mu(f_t) = \mu(f)$ follows from the item 2 of the Theorem 4.2.

If there exist $D_i^s = D_i$, we conclude that each Jacobian ideal $J(f_t)$ is non-degenerate for small values of t from the fact that the set of non-degenerate ideals on some Newton polyhedron is open for the Zariski topology.

Hence the equality $\mu(f_t) = \mu(f)$ follows from the item 2 of the Theorem 4.2. ■

The following example illustrates this result.

EXAMPLE 4.2. Let $f(x, y) = x^{12} + y^8$. Fix the Newton polyhedron $\Gamma_+ = \Gamma_+(f)$, since f is weighted homogeneous with respect to the weight $w = (2, 3)$, we obtain that Γ_+ has only one compact face with vertices $(12, 0)$ and $(0, 8)$. The jacobian ideal $J(f) = \langle f_x, f_y \rangle$ is non-degenerate on Γ_+ , with $d(f_x) = 22$ and $d(f_y) = 21$.

Consider the family $f_t(x, y) = x^{12} + y^8 - 2tx^6y^4$. Here $d(f_{tx}) = 22 = d(f_x)$ and $d(f_{ty}) = 21 = d(f_y)$. The principal part of the generators $\{f_{tx}, f_{ty}\}$ of the Jacobian ideal $J(f_t)$ is different from the principal part of the generators $\{f_x, f_y\}$ of the Jacobian ideal $J(f)$, but for each $0 \leq t < 1$, the system of generators $\{f_{tx}, f_{ty}\}$ is also non-degenerate, hence $\mu(f) = \mu(f_t)$ for all $0 \leq t < 1$. For $t = 1$, we see that the germ $f_1 = (x^6 - y^4)^2$ has not isolated singularity, hence $\mu(f_1) = \infty$.

We see in the example below that it is possible to find families f_t such that the germ f is non-degenerate, there exists a $t \neq 0$ such that f_t is degenerate, but the family f_t is also μ -constant.

EXAMPLE 4.3. Let $f(x, y, z) = x^2 + y^2 + xz + z^2$. The germ f is homogeneous and Newton non-degenerate. Consider the family $f_t = x^2 + y^2 + xz + z^2 + 2txy$. From the Theorem 4.3 we see that for $0 \leq t < 1$, $\mu(f_t) = \mu(f)$. When $t = 1$, the Jacobian ideal $J(f_1)$ is not Newton non-degenerate (see [5], pag. 08), but $\mu(f_1) = \mu(f)$.

On the other side, we can also prove the following

THEOREM 4.4. *Suppose that the system of generators $\{\partial f/\partial x_1, \dots, \partial f/\partial x_n\}$ of the Jacobian ideal $J(f)$ is non-degenerate on Γ_+ . If $\mu(f_t)$ is constant for small values of t and the system of generators $\{\partial f_t/\partial x_1, \dots, \partial f_t/\partial x_n\}$ is non-degenerate on Γ_+ , then $D_i^s \geq D_i$ for all $i = 1, \dots, n$ and all $s = 1, \dots, \ell$.*

Proof: If $\mu(f_t) = \mu(f)$, since $J(f_t)$ is non-degenerate on Γ_+ , it follows from the item 2 of the Theorem 4.2 that

$$\mu(f_t) = \frac{D_{t1} \cdots D_{tn}}{M^n} n! V_n(\Gamma_-) \text{ and } \mu(f) = \frac{D_1 \cdots D_n}{M^n} n! V_n(\Gamma_-).$$

From the hypothesis we have

$$\frac{D_{t1} \cdots D_{tn}}{M^n} n! V_n(\Gamma_-) = \frac{D_1 \cdots D_n}{M^n} n! V_n(\Gamma_-).$$

Hence we conclude that $D_{t1} \cdots D_{tn} = D_1 \cdots D_n$, but $D_{ti} = \min \{D_i, D_i^s\}$ for small values of t and all $i = 1 \dots, n$, $s = 1, \dots, \ell$.

Therefore we obtain $D_{ti} = D_i$ for all $i = 1 \dots, n$ and $D_i^s \geq D_i$ for all $i = 1 \dots, n$, $s = 1, \dots, \ell$. \blacksquare

EXAMPLE 4.4. Generalized Briançon-Speder Example

We shall consider here families of type $f_t(x, y, z) = z^5 + y^7x + x^{15} + tx^ay^bz^c$ for a fixed monomial $x^ay^bz^c$. In order to study the μ -constancy of this family, we first check when $x^ay^bz^c$ satisfies the necessary condition $\Gamma_+(x^ay^bz^c) \subseteq T(f)$ given in the Lemma 3.1.

The Jacobian ideal $J(f) = \langle 15x^{14} + y^7, 7y^6x, 5z^4 \rangle$, is Newton non-degenerate, hence $T(f) = \Gamma_+(J(f))$, whose vertices are $(14, 0, 0)$, $(0, 7, 0)$, $(1, 6, 0)$ and $(0, 0, 4)$ in \mathbb{R}_+^3 . Therefore, we consider the monomials $x^ay^bz^c$ such that $(a, b, c) \in \Gamma_+(J(f))$.

For instance, if we fix the monomial $x^ay^bz^c = y^6z$, we consider the Newton polyhedron Γ_+ with vertices $(3, 0, 0)$, $(0, 2, 0)$ and $(0, 0, 1)$, which has one 2-dimensional compact face associate to the weights $(1, 2, 3)$. An easy calculation shows that the Γ -order of the partial derivatives of f are: $d(15x^{14} + y^7) = 14$, $d(7y^6x) = 13$, $d(5z^4) = 12$ and $J(f)$ is non-degenerate on Γ_+ .

The Γ -order of the partial derivatives of the monomial y^6z are: $d(\partial(y^6z)/\partial x) = \infty$, $d(6y^5z) = 13$ and $d(y^6) = 12$, hence we apply the Theorem 4.3 to conclude that the system of generators $\{15x^{14} + y^7, 7y^6x + t6y^5z, 5z^4 + ty^6\}$ is non-degenerate on Γ_+ and the family f_t is μ -constant for small values of t .

Analogous argument can be applied to any family $f_t(x) = f + \sum_{s=1}^{\ell} \delta_s(t)g_s$ satisfying the conditions of the Theorem 4.3 for this Newton polyhedron.

But there are some monomials $x^ay^bz^c$ satisfying the condition $(a, b, c) \in \Gamma_+(J(f))$ which do not satisfy the conditions of the Theorem 4.3 for this Newton polyhedron. For example, if we consider $x^ay^bz^c = yz^4$, the Γ -order of $d(\partial(yz^4)/\partial y) = 11$ and we can not apply the Theorem 4.3.

On the other side we apply the Theorem 4.4 to show that the family $f_t(x, y, z) = z^5 + y^7x + x^{15} + tyz^4$ is not μ -constant. For this we fix the Newton polyhedron $\Gamma_+ = \Gamma_+(J(f_t))$. Here $J(f_t)$ is Newton non-degenerate and $J(f)$ is degenerate on this polyhedron, hence $\mu(f_t) < \mu(f)$ for all $t \neq 0$.

Analogous argument can be applied to any family $f_t(x) = f + \sum_{s=1}^{\ell} \delta_s(t)g_s$ such that $J(f_t)$ is Newton non-degenerate, the germs g_s satisfies the condition $\Gamma_+(g_s) \in \Gamma_+(J(f))$, but do not satisfies the condition of the Theorem 4.3.

5. μ -CONSTANT DEFORMATIONS AND THE MULTIPLICITY

The *multiplicity* of a germ $f(x) = \sum a_k x^k$, is defined as the lowest degree in the power series of $f(x)$.

Zariski proposed in [15] the following question:

Whether for a hypersurface singularity the multiplicity is an invariant of the topological type?

It is well known that this question has a positive answer in the case of plane curves and for quasi homogeneous complex hypersurfaces, as it is shown by Greuel in [4].

For the case of first order deformations $F(x, t) = f(x) + tg(x)$ of a complex germ f with isolated singularity, Trotman gives in [12] a positive answer for Zariski's question.

From the results given in the section 4 we obtain a positive answer for Zariski's question for families $F(x, t) = f(x) + \sum_{s=1}^{\ell} \delta_s(t)g_s(t)$ of germs which are non-degenerate on some Newton polyhedron Γ_+ .

COROLLARY 5.1. *Let $F(x, t) = f(x) + \sum_{s=1}^{\ell} \delta_s(t)g_s(t)$ be a deformation of a germ f with isolated singularity. Suppose that for small values of t , the system of generators $\left\{ \frac{\partial f_t}{\partial x_1}, \dots, \frac{\partial f_t}{\partial x_n} \right\}$ of each Jacobian ideal $J(f_t)$ is non-degenerate on Γ_+ . If $\mu(f_t)$ is constant, then $F(x, t)$ is m -constant.*

Proof: From the hypothesis and the Theorem 4.4 we conclude that $D_i^s \geq D_i$ for all $i = 1, \dots, n$ and all $s = 1, \dots, \ell$, therefore $\Gamma_+(g_s) \subset \Gamma_+(f)$ for all $s = 1, \dots, \ell$, hence the equality $m(f_t) = m(f)$ follows. ■

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